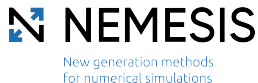


# Implementation aspects of polytopal methods and handling of polytopal meshes in HArDCore

Jérôme Droniou



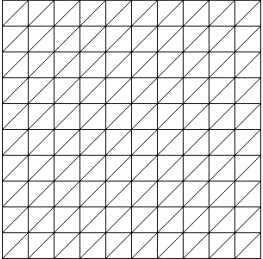
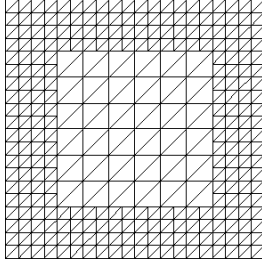
Towards polytopal meshes in GMSH  
Montpellier, 26–27 January 2026



- 1 Polytopal methods: examples of practical efficiency
- 2 Implementing HHO
- 3 Bases for polynomial spaces on cells, faces, edges
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# Reissner–Mindlin plate problem

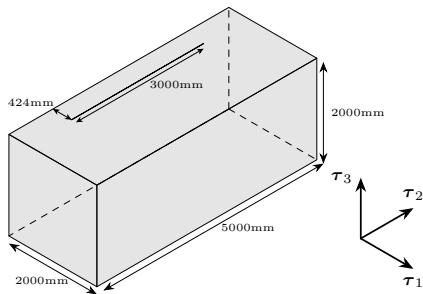
[Di Pietro and Droniou, 2022]

Stabilised $\mathcal{P}^2$ -( $\mathcal{P}^1 + \mathcal{B}^3$ ) scheme		DDR scheme	
			
nb. DOFs	Error	nb. DOFs	Error
2403	0.138	550	0.161
9603	6.82e-2	2121	6.77e-2
38402	3.40e-2	8329	3.1e-2

# Electromagnetic wave I

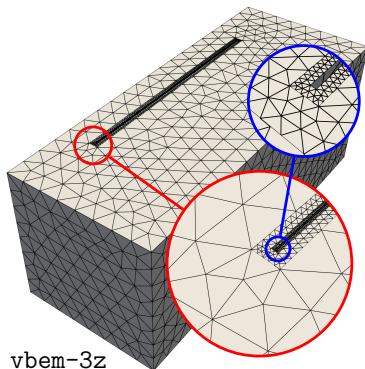
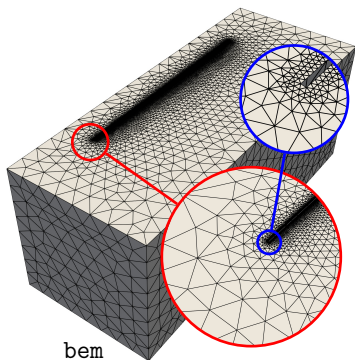
[Touzalín, 2025]

**Problem:** use a boundary element method to analyse the shielding effectiveness of a perfectly conductive box with a very small slit.



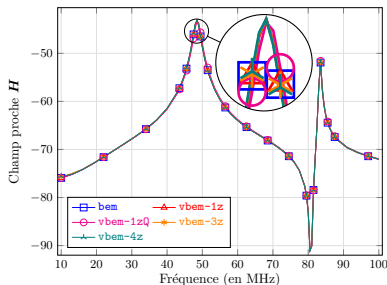
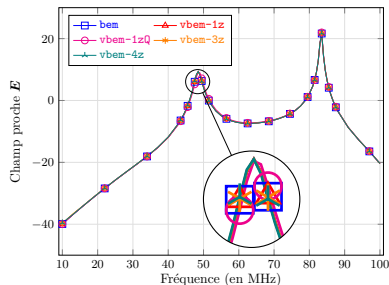
# Electromagnetic wave II

**Meshes:** conforming triangular for finite-element boundary method (bem), non-conforming triangular (polygonal) for virtual element boundary method (vbem-3z).



# Electromagnetic wave III

**Accuracy:** comparison of modulus of reflected near fields at the top.



**Computational cost**

<i>Method</i>	<i>Assembly</i>	<i>Resolution</i>
bem	813s	125s
vbem-3z	321s	19s

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# Algebraic realisation of potential

■ Space:  $\underline{V}_T^k = \{ \underline{v}_T = (v_T, (v_F)_{F \in \mathcal{F}_T}) : v_T \in \mathcal{P}^{k-1}(T), v_F \in \mathcal{P}^k(F) \}$ .

■ Potential reconstruction ( $k \geq 1$ ):

$$\int_T \nabla p_T^{k+1} \underline{v}_T \cdot \nabla w = - \int_T v_T \Delta w + \sum_{F \in \mathcal{F}_T} \int_F v_F (\nabla w \cdot \mathbf{n}_{TF}) \quad \forall w \in \mathcal{P}^{k+1}(T),$$

$$\int_T p_T^{k+1} \underline{v}_T = \int_T v_T.$$

■ Recast as: for all  $w \in \mathcal{P}^{k+1}(T)$ ,

$$\begin{aligned} (\nabla p_T^{k+1} \underline{v}_T, \nabla w)_T + (p_T^{k+1} \underline{v}_T, 1)_T (w, 1)_T \\ = -(v_T, \Delta w)_T + \sum_{F \in \mathcal{F}_T} (v_F, \nabla w \cdot \mathbf{n}_{TF})_F + (v_T, 1)_T (w, 1)_T. \end{aligned}$$

*(Solution of a Riesz representation problem)*



# Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- Pick bases  $\Phi_F^k$  of  $\mathcal{P}^k(F)$  for  $F \in \mathcal{F}_T$  and  $\Phi_T^{k-1}$  of  $\mathcal{P}^{k-1}(T)$ .

$$\text{Basis of } \underline{V}_T^k : \Phi_{F_1}^k \times \cdots \times \Phi_{F_{N\partial T}}^k \times \Phi_T^{k-1}.$$

*(Increasing dimension of mesh entities)*

- Pick basis  $\widehat{\Phi}_T^{k+1}$  of  $\mathcal{P}^{k+1}(T)$ .

# Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- Pick bases  $\Phi_F^k$  of  $\mathcal{P}^k(F)$  for  $F \in \mathcal{F}_T$  and  $\Phi_T^{k-1}$  of  $\mathcal{P}^{k-1}(T)$ .

$$\text{Basis of } \underline{V}_T^k : \Phi_{F_1}^k \times \cdots \times \Phi_{F_{N_{\partial T}}}^k \times \Phi_T^{k-1}.$$

*(Increasing dimension of mesh entities)*

- Pick basis  $\widehat{\Phi}_T^{k+1}$  of  $\mathcal{P}^{k+1}(T)$ .

- Notations:

$$\begin{aligned}\Phi_F^k &= \{\varphi_1^F, \dots, \varphi_{N_{k,F}}^F\}, \\ \Phi_T^{k-1} &= \{\varphi_1^T, \dots, \varphi_{N_{k,T}}^T\}, \\ \widehat{\Phi}_T^{k+1} &= \{\widehat{\varphi}_1^T, \dots, \widehat{\varphi}_{N_{k+1,T}}^T\}.\end{aligned}$$

# Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- Pick bases  $\Phi_F^k$  of  $\mathcal{P}^k(F)$  for  $F \in \mathcal{F}_T$  and  $\Phi_T^{k-1}$  of  $\mathcal{P}^{k-1}(T)$ .

$$\text{Basis of } \underline{V}_T^k : \Phi_{F_1}^k \times \cdots \times \Phi_{F_{N_{\partial T}}}^k \times \Phi_T^{k-1}.$$

*(Increasing dimension of mesh entities)*

- Pick basis  $\widehat{\Phi}_T^{k+1}$  of  $\mathcal{P}^{k+1}(T)$ .
- Notations: vector  $\underline{V}_T$  of  $\underline{v}_T \in \underline{V}_T^k$  written as:

$$\underline{V}_T = \begin{bmatrix} V_{F_1} \\ \vdots \\ V_{F_{N_{\partial T}}} \\ V_T \end{bmatrix} \quad \text{with} \quad \begin{aligned} V_F &= [V_i^F]_{i=1, \dots, N_{k,F}} \text{ coefficients on } \Phi_F^k, \\ V_T &= [V_i^T]_{i=1, \dots, N_{k-1,T}} \text{ coefficients on } \Phi_T^{k-1}. \end{aligned}$$

# Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

## ■ Definition:

$$\begin{aligned} (\nabla \underline{p}_T^{k+1} \underline{v}_T, \nabla w)_T + (\underline{p}_T^{k+1} \underline{v}_T, 1)_T (w, 1)_T \\ = -(\underline{v}_T, \Delta w)_T + (\underline{v}_T, 1)_T (w, 1)_T + \sum_{F \in \mathcal{F}_T} (\underline{v}_F, \nabla w \cdot \underline{n}_{TF})_F. \end{aligned}$$

## ■ Algebraic translation: the coefficients $\mathbf{P}_T$ of $p_T^{k+1} \underline{v}_T$ on $\widehat{\Phi}_T^{k+1}$ satisfy

$$\left( \mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \left( \mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \right) \mathbf{V}_T + \sum_{F \in \mathcal{F}_T} \mathbf{B}_{P,F} \mathbf{V}_F,$$

with

$$\begin{aligned} \mathbf{S}_T &:= [(\nabla \widehat{\varphi}_i^T, \nabla \widehat{\varphi}_j^T)_T]_{1 \leq i, j \leq N_{k+1,T}}, \quad \widehat{\mathbf{L}}_T^{k+1} := [(\widehat{\varphi}_i^T, 1)_T]_{1 \leq i \leq N_{k+1,T}}, \\ \mathbf{B}_{P,T} &:= [-(\Delta \widehat{\varphi}_i^T, \varphi_j^T)_T]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k-1,T}}, \quad \mathbf{L}_T^{k-1} := [(\varphi_i^T, 1)_T]_{1 \leq i \leq N_{k-1,T}}, \\ \mathbf{B}_{P,F} &:= [(\nabla \widehat{\varphi}_i^T \cdot \underline{n}_{TF}, \varphi_j^F)_F]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k,F}}. \end{aligned}$$

# Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- The coefficients  $\mathbf{P}_T$  of  $p_T^{k+1} \underline{v}_T$  on  $\widehat{\Phi}_T^{k+1}$  satisfy

$$\left( \mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \left( \mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \right) \mathbf{V}_T + \sum_{F \in \mathcal{F}_T} \mathbf{B}_{P,F} \mathbf{V}_F,$$

$$\mathbf{S}_T := [(\nabla \widehat{\varphi}_i^T, \nabla \widehat{\varphi}_j^T)_T]_{1 \leq i, j \leq N_{k+1,T}}, \quad \widehat{\mathbf{L}}_T^{k+1} := [(\widehat{\varphi}_i^T, 1)_T]_{1 \leq i \leq N_{k+1,T}},$$

$$\mathbf{B}_{P,T} := [-(\Delta \widehat{\varphi}_i^T, \varphi_j^T)_T]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k-1,T}}, \quad \mathbf{L}_T^{k-1} := [(\varphi_i^T, 1)_T]_{1 \leq i \leq N_{k-1,T}},$$

$$\mathbf{B}_{P,F} := [(\nabla \widehat{\varphi}_i^T \cdot \mathbf{n}_{TF}, \varphi_j^F)_F]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k,F}}.$$

- The matrix  $\mathbf{P}_T$  of  $p_T^{k+1}$  is thus obtained by solving

$$\left( \mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \begin{bmatrix} \mathbf{B}_{P,F_1} & \cdots & \mathbf{B}_{P,F_{N_{\partial T}}} & \mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \end{bmatrix}.$$

# Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- The coefficients  $P_T$  of  $p_T^{k+1} \underline{v}_T$  on  $\widehat{\Phi}_T^{k+1}$  satisfy

$$\left( \mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \left( \mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \right) \mathbf{V}_T + \sum_{F \in \mathcal{F}_T} \mathbf{B}_{P,F} \mathbf{V}_F,$$

$$\mathbf{S}_T := [(\nabla \widehat{\varphi}_i^T, \nabla \widehat{\varphi}_j^T)_T]_{1 \leq i, j \leq N_{k+1,T}}, \quad \widehat{\mathbf{L}}_T^{k+1} := [(\widehat{\varphi}_i^T, 1)_T]_{1 \leq i \leq N_{k+1,T}},$$

$$\mathbf{B}_{P,T} := [-(\Delta \widehat{\varphi}_i^T, \varphi_j^T)_T]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k-1,T}}, \quad \mathbf{L}_T^{k-1} := [(\varphi_i^T, 1)_T]_{1 \leq i \leq N_{k-1,T}},$$

$$\mathbf{B}_{P,F} := [(\nabla \widehat{\varphi}_i^T \cdot \mathbf{n}_{TF}, \varphi_j^F)_F]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k,F}}.$$

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- A few requirements for the library:
  - Gram matrices of families of polynomials (integrate products).
  - Differential operators between families of polynomials.
  - Direct access to faces of an elements, and integrate on them.

- Linear algebra: via Eigen (<https://gitlab.com/libeigen/eigen>).
- In-house **Mesh classes** and **Polynomial family classes**.
- **Fast integration rules** [Chin et al., 2015]: essential for polytopal methods, requires full connectivity from element to vertices, as well as geometric information (outer normal, etc.).  
*(In some instances, quadrature-based integration is still required.)*
- Various interfaces:
  - ★ PaSTiX (<https://solverstack.gitlabpages.inria.fr/pastix/>),
  - ★ PETSc (<https://petsc.org/release/>),
  - ★ etc.
- Many polytopal methods and schemes : HHO, DDR, VEM, elasticity with Tresca contact, plates, Yang–Mills, etc.

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# Construction of polynomial bases

- Store vectors of powers up to degree  $\ell$

$$\{\boldsymbol{\alpha} = (\omega_1, \dots, \omega_d) \in \mathbb{N}^d : \sum_i \omega_i = \ell\} = \{\boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \dots, \boldsymbol{\alpha}_{N_\ell}\},$$

which define the monomials ( $\mathbf{x}_T$  = center of mass of  $T$ ,  $h_T$  = diameter)

$$m_j(\mathbf{x}) = \left( \frac{x_1 - x_{T,1}}{h_T} \right)^{\alpha_{j,1}} \cdots \left( \frac{x_1 - x_{T,d}}{h_T} \right)^{\alpha_{j,d}}.$$

- Basis  $\Phi_T^\ell = \{\phi_1, \dots, \phi_{N_\ell}\}$  of  $\mathcal{P}^\ell(T)$ : linear combination of monomials

$$\phi_r = \sum_{j=1}^{N_\ell} M_{rj} m_j.$$

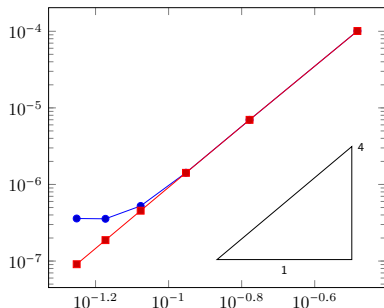
- Extensions: **vector- or matrix-valued** polynomials by tensorisation.
- **PolynomialFamily**: defined by **degree**  $\ell$ , **mesh entity** ( $T$ ,  $F$ , etc.), **generators** (list of scalars, vectors, matrices) and **matrix**  $M$ .



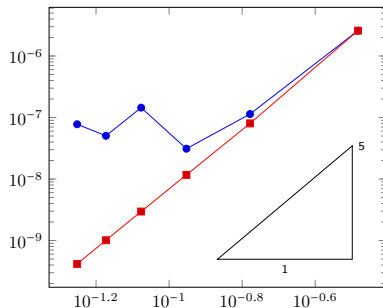
# Construction of polynomial bases

**Local polynomial bases on  $\mathcal{P}^k(T)$ ,  $\mathcal{P}^k(F)$  are orthonormalised!**

—●— Monomial basis functions —■— Orthonormal basis functions



(a) Energy norm vs.  $h$ , Kershaw meshes,  $k = 3$ .



(b)  $L^2$ -norm vs.  $h$ , Kershaw meshes,  $k = 3$ .

# Unified class for all kinds of polynomial spaces

- **PolynomialFamily**: defined by **degree**  $\ell$ , **mesh entity** ( $T$ ,  $F$ , etc.), **generators** (list of scalars, vectors, matrices) and **matrix**  $M$ .
- Suitable choices of generators and matrix describe **PolynomialFamilies** that are not  $\mathcal{P}^\ell(X)$ .

*For example, for PF polynomial family:*

- ★ **gradient**(PF), **divergence**(PF), **curl**(PF), etc.
- ★  $L$ (PF) if  $L$  linear map acting on generators.
- ★  $\text{PF}_1 + \text{PF}_2$  (sum of spanned vector spaces).

# Unified class for all kinds of polynomial spaces

- **PolynomialFamily**: defined by **degree**  $\ell$ , **mesh entity** ( $T$ ,  $F$ , etc.), **generators** (list of scalars, vectors, matrices) and **matrix**  $M$ .
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*For example, for PF polynomial family:*
  - ★ **gradient**(PF), **divergence**(PF), **curl**(PF), etc.
  - ★  $L$ (PF) if  $L$  linear map acting on generators.
  - ★  $\text{PF}_1 + \text{PF}_2$  (sum of spanned vector spaces).
- Koszul complements are also described as **PolynomialFamilies**, e.g.:

$$\mathcal{R}^{c,\ell}(T) = (\mathbf{x} - \mathbf{x}_T)\mathcal{P}^{\ell-1}(T), \quad \mathcal{G}^{c,\ell}(T) = (\mathbf{x} - \mathbf{x}_T) \times \mathcal{P}^{\ell-1}(T)^3.$$

*(leads to straightforward description of arbitrary-order Nédélec and Raviart–Thomas elements)*

- Unified class of polynomials means **unified (fast) integration rules**.



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# Classes for mesh entities

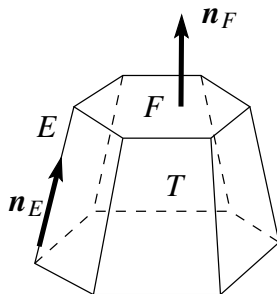
- Classes for **Cell**, **Face**, **Edge**, **Vertex**.

*All templated versions of the same **MeshObject** class.*

- **Full connectivity**, for example each **Face** embeds (pointers to) its neighbouring **Cells**, and the **Edges**, **Vertex** it contains.

*Useful for local constructions of operators, and fast integration rule.*

- Lots of additional **embedded information** (where relevant): global index; diameter, volume/area/length; center of mass; outer normal, tangent vector; relative orientations of sub-mesh entities; etc.



# Classes for mesh entities

- Classes for **Cell**, **Face**, **Edge**, **Vertex**.

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*Useful for local constructions of operators, and fast integration rule.*

- Lots of additional **embedded information** (where relevant): global index; diameter, volume/area/length; center of mass; outer normal, tangent vector; relative orientations of sub-mesh entities; etc.

- **Other features:**

- ★ Each cell/face has a simplicial subdivision.
- ★ 2-level meshes can be handled (coarsened mesh from fine mesh).
- ★ Mesh transformation/handlers: move vertices; split non-planar faces; etc.



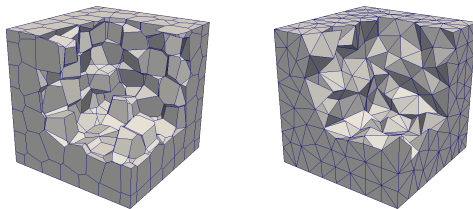
- Full mesh described in (large) “RF” mesh files with minimal (non-redundant) information.
- **MeshBuilder** takes care of creating all the connectivity.

*Since last October, the development version of HArDCore also has an interface with GMesh (<https://gmsh.info/>).*



# RF mesh file data structure

- Two files for each 3D mesh: M.node for vertices, M.ele for cells.
- In M.node, one line per vertex:  
<vertex id> <x coordinate> <y coordinate> <z coordinate>
- In M.ele, each cell is given by:
  - ★ Header line: <cell id> <number of faces>
  - ★ For each face in the cell:  
<local face id> <number of vertices> <id of first vertex> <id of second vertex> ...  
(vertices listed in order around the face boundary)



- From RF file or GMesh mesh, creates `std::vector` to list vertices and cells (as in RF file format).
- To create a mesh entity in **Mesh**, it is split into simplices:
  - ★ ensures that orientation will be correct,
  - ★ allows for calculation of center of mass, measure, etc.  
*(Assumes that faces and cells are star-shaped w.r.t. average of their vertices).*
- Entities (partially) created and added by increasing dimension:
  - ★ Vertices (no connectivity at this stage).
  - ★ Edges (connected to vertices and gives connexion between vertices).
  - ★ etc.

# Conclusion and transition

- Building polytopal schemes requires:
  - ★ Selecting **degrees of freedom** (*polynomials on vertices, edges, faces, elements*).
  - ★ Implementing **reconstruction operators** as the solutions to **local problems** (*Riez representation problems*).

**No need for explicit shape functions.**

- Same approach can be applied to **(complex) finite elements**, without having to know their shape functions (*typically challenging in some FE for elasticity*).
- Coding polytopal methods is facilitated by a **rich mesh structure**, well-suited **polynomial bases** and efficient libraries for **polynomial integration**.



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**Thank you for your attention!**



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