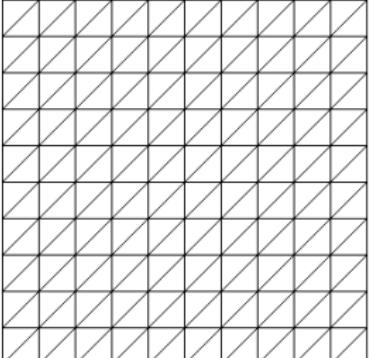
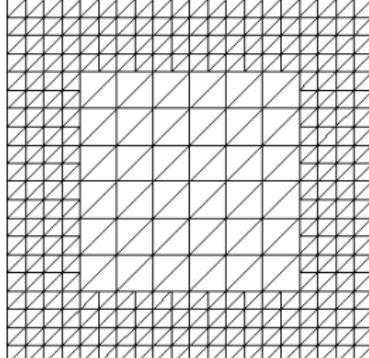


Reissner–Mindlin plate problem

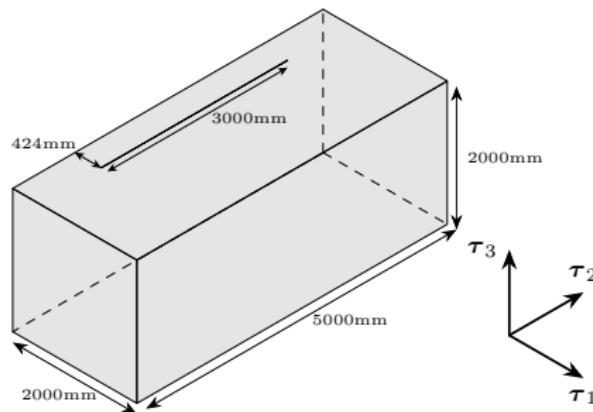
[Di Pietro and Droniou, 2022]

Stabilised \mathcal{P}^2 - $(\mathcal{P}^1 + \mathcal{B}^3)$ scheme		DDR scheme	
			
nb. DOFs	Error	nb. DOFs	Error
2403	0.138	550	0.161
9603	6.82e-2	2121	6.77e-2
38402	3.40e-2	8329	3.1e-2

Electromagnetic wave I

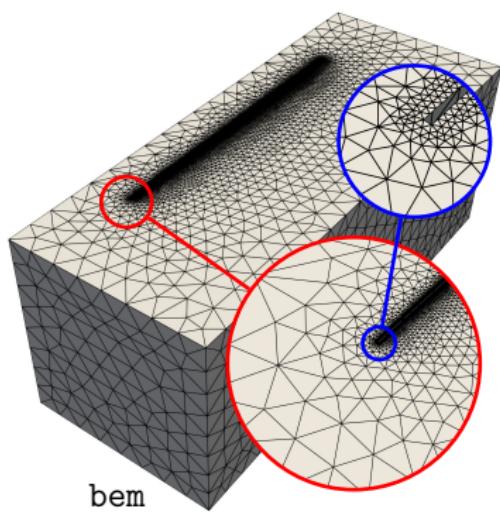
[Touzalin, 2025]

Problem: use a boundary element method to analyse the shielding effectiveness of a perfectly conductive box with a very small slit.

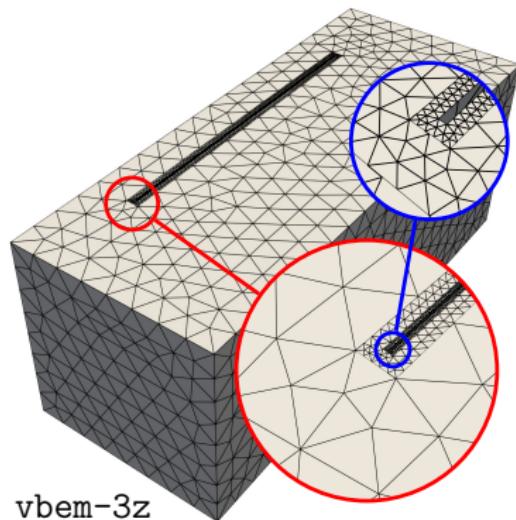


Electromagnetic wave II

Meshes: conforming triangular for finite-element boundary method (bem), non-conforming triangular (polygonal) for virtual element boundary method (vbem-3z).



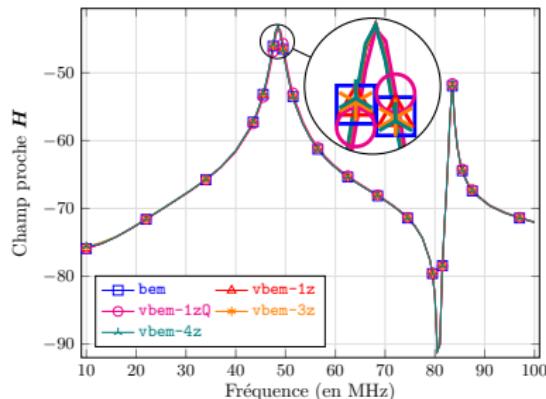
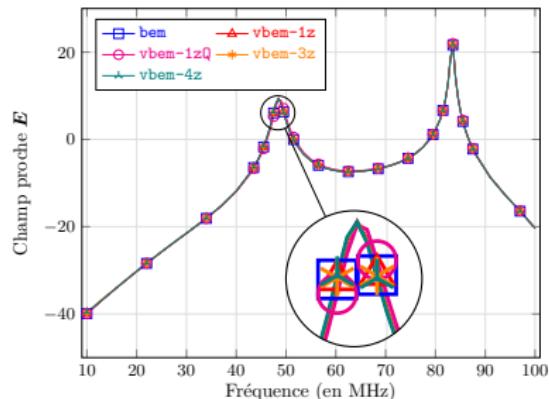
bem



vbem-3z

Electromagnetic wave III

Accuracy: comparison of modulus of reflected near fields at the top.



Computational cost

<i>Method</i>	<i>Assembly</i>	<i>Resolution</i>
bem	813s	125s
vbem-3z	321s	19s

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Algebraic realisation of potential

- Space: $\underline{V}_T^k = \{v_T = (v_T, (v_F)_{F \in \mathcal{F}_T}) : v_T \in \mathcal{P}^{k-1}(T), v_F \in \mathcal{P}^k(F)\}$.

- Potential reconstruction ($k \geq 1$):

$$\int_T \nabla p_T^{k+1} \underline{v}_T \cdot \nabla w = - \int_T v_T \Delta w + \sum_{F \in \mathcal{F}_T} \int_F v_F (\nabla w \cdot \mathbf{n}_{TF}) \quad \forall w \in \mathcal{P}^{k+1}(T),$$

$$\int_T p_T^{k+1} \underline{v}_T = \int_T v_T.$$

- Recast as: for all $w \in \mathcal{P}^{k+1}(T)$,

$$\begin{aligned} (\nabla p_T^{k+1} \underline{v}_T, \nabla w)_T + (p_T^{k+1} \underline{v}_T, 1)_T (w, 1)_T \\ = -(v_T, \Delta w)_T + \sum_{F \in \mathcal{F}_T} (v_F, \nabla w \cdot \mathbf{n}_{TF})_F + (v_T, 1)_T (w, 1)_T. \end{aligned}$$

(Solution of a Riesz representation problem)



Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- Pick bases Φ_F^k of $\mathcal{P}^k(F)$ for $F \in \mathcal{F}_T$ and Φ_T^{k-1} of $\mathcal{P}^{k-1}(T)$.

Basis of \underline{V}_T^k : $\Phi_{F_1}^k \times \cdots \times \Phi_{F_{N_{\partial T}}}^k \times \Phi_T^{k-1}$.

(Increasing dimension of mesh entities)

- Pick basis $\widehat{\Phi}_T^{k+1}$ of $\mathcal{P}^{k+1}(T)$.

- Notations:

$$\Phi_F^k = \{\varphi_1^F, \dots, \varphi_{N_{k,F}}^F\},$$

$$\Phi_T^{k-1} = \{\varphi_1^{T-1}, \dots, \varphi_{N_{k,T}}^{T-1}\},$$

$$\widehat{\Phi}_T^{k+1} = \{\widehat{\varphi}_1^{T+1}, \dots, \widehat{\varphi}_{N_{k+1,T}}^{T+1}\}.$$



Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- Pick bases Φ_F^k of $\mathcal{P}^k(F)$ for $F \in \mathcal{F}_T$ and Φ_T^{k-1} of $\mathcal{P}^{k-1}(T)$.

Basis of \underline{V}_T^k : $\Phi_{F_1}^k \times \cdots \times \Phi_{F_{N_{\partial T}}}^k \times \Phi_T^{k-1}$.

(Increasing dimension of mesh entities)

- Pick basis $\widehat{\Phi}_T^{k+1}$ of $\mathcal{P}^{k+1}(T)$.
- Notations: vector \underline{v}_T of $v_T \in \underline{V}_T^k$ written as:

$$\underline{v}_T = \begin{bmatrix} v_{F_1} \\ \vdots \\ v_{F_{N_{\partial T}}} \\ v_T \end{bmatrix} \quad \text{with} \quad \begin{aligned} v_F &= [v_i^F]_{i=1, \dots, N_{k,F}} \text{ coefficients on } \Phi_F^k, \\ v_T &= [v_i^T]_{i=1, \dots, N_{k-1,T}} \text{ coefficients on } \Phi_T^{k-1}. \end{aligned}$$



Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

■ Definition:

$$\begin{aligned} (\nabla \mathbf{p}_T^{k+1} \underline{v}_T, \nabla w)_T + (\mathbf{p}_T^{k+1} \underline{v}_T, 1)_T (w, 1)_T \\ = -(\mathbf{v}_T, \Delta w)_T + (\mathbf{v}_T, 1)_T (w, 1)_T + \sum_{F \in \mathcal{F}_T} (\mathbf{v}_F, \nabla w \cdot \mathbf{n}_{TF})_F. \end{aligned}$$

■ Algebraic translation: the coefficients \mathbf{P}_T of $p_T^{k+1} \underline{v}_T$ on $\widehat{\Phi}_T^{k+1}$ satisfy

$$\left(\mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \left(\mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \right) \mathbf{V}_T + \sum_{F \in \mathcal{F}_T} \mathbf{B}_{P,F} \mathbf{V}_F,$$

with

$$\mathbf{S}_T := [(\nabla \widehat{\varphi}_i^T, \nabla \widehat{\varphi}_j^T)_T]_{1 \leq i, j \leq N_{k+1,T}}, \quad \widehat{\mathbf{L}}_T^{k+1} := [(\widehat{\varphi}_i^T, 1)_T]_{1 \leq i \leq N_{k+1,T}},$$

$$\mathbf{B}_{P,T} := [(-(\Delta \widehat{\varphi}_i^T, \varphi_j^T)_T]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k-1,T}}, \quad \mathbf{L}_T^{k-1} := [(\varphi_i^T, 1)_T]_{1 \leq i \leq N_{k-1,T}}$$

$$\mathbf{B}_{P,F} := [(\nabla \widehat{\varphi}_i^T \cdot \mathbf{n}_{TF}, \varphi_j^F)_F]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k,F}}.$$

Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- The coefficients \mathbf{P}_T of $p_T^{k+1} \underline{v}_T$ on $\widehat{\Phi}_T^{k+1}$ satisfy

$$\left(\mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \left(\mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \right) \mathbf{V}_T + \sum_{F \in \mathcal{F}_T} \mathbf{B}_{P,F} \mathbf{V}_F,$$

$$\mathbf{S}_T := \left[(\nabla \widehat{\varphi}_i^T, \nabla \widehat{\varphi}_j^T)_T \right]_{1 \leq i, j \leq N_{k+1,T}}, \quad \widehat{\mathbf{L}}_T^{k+1} := [(\widehat{\varphi}_i^T, 1)_T]_{1 \leq i \leq N_{k+1,T}},$$

$$\mathbf{B}_{P,T} := \left[-(\Delta \widehat{\varphi}_i^T, \varphi_j^T)_T \right]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k-1,T}}, \quad \mathbf{L}_T^{k-1} := [(\varphi_i^T, 1)_T]_{1 \leq i \leq N_{k-1,T}}$$

$$\mathbf{B}_{P,F} := \left[(\nabla \widehat{\varphi}_i^T \cdot \mathbf{n}_{TF}, \varphi_j^F)_F \right]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k,F}}.$$

- The matrix \mathbf{P}_T of p_T^{k+1} is thus obtained by solving

$$\left(\mathbf{S}_T + \widehat{\mathbf{L}}_T^{k+1} (\widehat{\mathbf{L}}_T^{k+1})^\top \right) \mathbf{P}_T = \left[\mathbf{B}_{P,F_1} \quad \cdots \quad \mathbf{B}_{P,F_{N_{\partial T}}} \quad \mathbf{B}_{P,T} + \widehat{\mathbf{L}}_T^{k+1} (\mathbf{L}_T^{k-1})^\top \right].$$

Matrix of $p_T^{k+1} : \underline{V}_T^k \rightarrow \mathcal{P}^{k+1}(T)$ on selected bases

- The coefficients \mathbf{P}_T of $p_T^{k+1} \underline{v}_T$ on $\widehat{\Phi}_T^{k+1}$ satisfy

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$$\mathbf{S}_T := \left[(\nabla \widehat{\varphi}_i^T, \nabla \widehat{\varphi}_j^T)_T \right]_{1 \leq i, j \leq N_{k+1,T}}, \quad \widehat{\mathbf{L}}_T^{k+1} := [(\widehat{\varphi}_i^T, 1)_T]_{1 \leq i \leq N_{k+1,T}},$$

$$\mathbf{B}_{P,T} := \left[-(\Delta \widehat{\varphi}_i^T, \varphi_j^T)_T \right]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k-1,T}}, \quad \mathbf{L}_T^{k-1} := [(\varphi_i^T, 1)_T]_{1 \leq i \leq N_{k-1,T}}$$

$$\mathbf{B}_{P,F} := \left[(\nabla \widehat{\varphi}_i^T \cdot \mathbf{n}_{TF}, \varphi_j^F)_F \right]_{1 \leq i \leq N_{k+1,T}, 1 \leq j \leq N_{k,F}}.$$

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- A few requirements for the library:

- Gram matrices of families of polynomials (integrate products).
- Differential operators between families of polynomials.
- Direct access to faces of an elements, and integrate on them.



- Linear algebra: via Eigen (<https://gitlab.com/libeigen/eigen>).
- In-house **Mesh classes** and **Polynomial family classes**.
- **Fast integration rules** [Chin et al., 2015]: essential for polytopal methods, requires full connectivity from element to vertices, as well as geometric information (outer normal, etc.).
(In some instances, quadrature-based integration is still required.)
- Various interfaces:
 - ★ PaSTiX (<https://solverstack.gitlabpages.inria.fr/pastix/>),
 - ★ PETSc (<https://petsc.org/release/>),
 - ★ etc.
- Many polytopal methods and schemes : HHO, DDR, VEM, elasticity with Tresca contact, plates, Yang–Mills, etc.

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Construction of polynomial bases

- Store vectors of powers up to degree ℓ

$$\{\boldsymbol{\alpha} = (\omega_1, \dots, \omega_d) \in \mathbb{N}^d : \sum_i \omega_i = \ell\} = \{\boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \dots, \boldsymbol{\alpha}_{N_\ell}\},$$

which define the monomials (\mathbf{x}_T = center of mass of T , h_T = diameter)

$$m_j(\mathbf{x}) = \left(\frac{x_1 - x_{T,1}}{h_T} \right)^{\alpha_{j,1}} \cdots \left(\frac{x_1 - x_{T,d}}{h_T} \right)^{\alpha_{j,d}}.$$

- Basis $\Phi_T^\ell = \{\phi_1, \dots, \phi_{N_\ell}\}$ of $\mathcal{P}^\ell(T)$: linear combination of monomials

$$\phi_r = \sum_{j=1}^{N_\ell} M_{r,j} m_j.$$

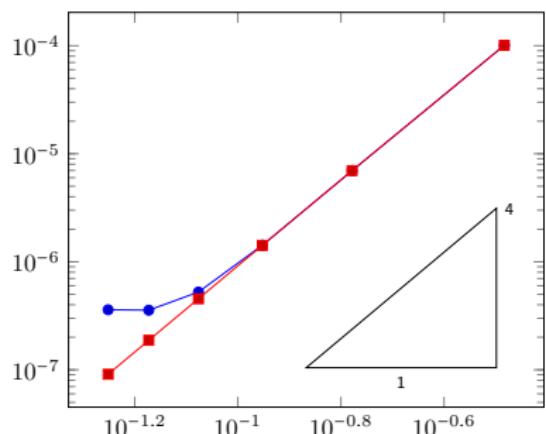
- Extensions: **vector- or matrix-valued** polynomials by tensorisation.
- **PolynomialFamily**: defined by **degree** ℓ , **mesh entity** (T , F , etc.), **generators** (list of scalars, vectors, matrices) and **matrix** M .



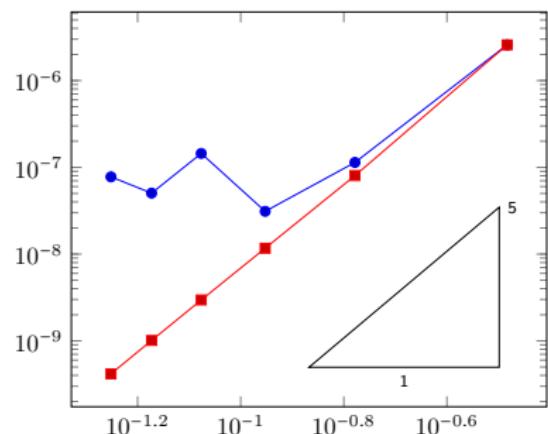
Construction of polynomial bases

Local polynomial bases on $\mathcal{P}^k(T)$, $\mathcal{P}^k(F)$ are orthonormalised!

●—● Monomial basis functions ■—■ Orthonormal basis functions



(a) Energy norm vs. h , Kershaw meshes,
 $k = 3$.



(b) L^2 -norm vs. h , Kershaw meshes,
 $k = 3$.

Unified class for all kinds of polynomial spaces

- **PolynomialFamily**: defined by **degree ℓ** , **mesh entity** (T , F , etc.), **generators** (list of scalars, vectors, matrices) and **matrix M** .
- Suitable choices of generators and matrix describe **PolynomialFamilies** that are not $\mathcal{P}^\ell(X)$.

For example, for PF polynomial family:

- ★ **gradient(PF)**, **divergence(PF)**, **curl(PF)**, etc.
- ★ $L(\text{PF})$ if L linear map acting on generators.
- ★ $\text{PF}_1 + \text{PF}_2$ (sum of spanned vector spaces).



Unified class for all kinds of polynomial spaces

- **PolynomialFamily**: defined by **degree ℓ** , **mesh entity** (T , F , etc.), **generators** (list of scalars, vectors, matrices) and **matrix M** .
- Suitable choices of generators and matrix describe **PolynomialFamilies** that are not $\mathcal{P}^\ell(X)$.
For example, for PF polynomial family:
 - ★ **gradient(PF)**, **divergence(PF)**, **curl(PF)**, etc.
 - ★ $L(\text{PF})$ if L linear map acting on generators.
 - ★ $\text{PF}_1 + \text{PF}_2$ (sum of spanned vector spaces).
- Koszul complements are also described as **PolynomialFamilies**, e.g.:

$$\mathcal{R}^{c,\ell}(T) = (\mathbf{x} - \mathbf{x}_T) \mathcal{P}^{\ell-1}(T), \quad \mathcal{G}^{c,\ell}(T) = (\mathbf{x} - \mathbf{x}_T) \times \mathcal{P}^{\ell-1}(T)^3.$$

(leads to straightforward description of arbitrary-order Nédélec and Raviart–Thomas elements)

- Unified class of polynomials means **unified (fast) integration rules**.



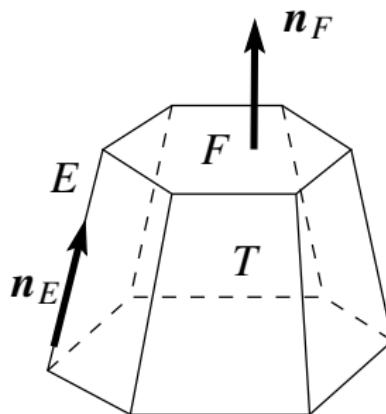
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Classes for mesh entities

- Classes for **Cell**, **Face**, **Edge**, **Vertex**.
All templated versions of the same MeshObject class.
- **Full connectivity**, for example each **Face** embeds (pointers to) its neighbouring **Cells**, and the **Edges**, **Vertex** it contains.
Useful for local constructions of operators, and fast integration rule.
- Lots of additional **embedded information** (where relevant): global index; diameter, volume/area/length; center of mass; outer normal, tangent vector; relative orientations of sub-mesh entities; etc.



Classes for mesh entities

- Classes for **Cell**, **Face**, **Edge**, **Vertex**.
*All templated versions of the same **MeshObject** class.*
- **Full connectivity**, for example each **Face** embeds (pointers to) its neighbouring **Cells**, and the **Edges**, **Vertex** it contains.
Useful for local constructions of operators, and fast integration rule.
- Lots of additional **embedded information** (where relevant): global index; diameter, volume/area/length; center of mass; outer normal, tangent vector; relative orientations of sub-mesh entities; etc.
- **Other features:**
 - ★ Each cell/face has a simplicial subdivision.
 - ★ 2-level meshes can be handled (coarsened mesh from fine mesh).
 - ★ Mesh transformation/handlers: move vertices; split non-planar faces; etc.



Mesh construction

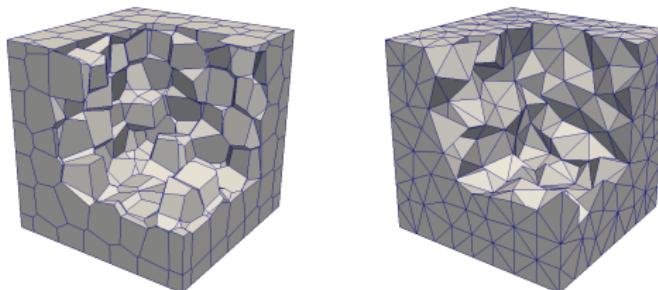
- Full mesh described in (large) “RF” mesh files with minimal (non-redundant) information.
- **MeshBuilder** takes care of creating all the connectivity.

Since last October, the development version of HArDCore also has an interface with GMesh (<https://gmsh.info/>).



RF mesh file data structure

- Two files for each 3D mesh: `M.node` for vertices, `M.ele` for cells.
- In `M.node`, one line per vertex:
`<vertex id> <x coordinate> <y coordinate> <z coordinate>`
- In `M.ele`, each cell is given by:
 - ★ Header line: `<cell id> <number of faces>`
 - ★ For each face in the cell:
`<local face id> <number of vertices> <id of first vertex> <id of second vertex> ...`
(vertices listed in order around the face boundary)



Mesh builder

- From RF file or GMesh mesh, creates `std::vector` to list vertices and cells (as in RF file format).
- To create a mesh entity in `Mesh`, it is split into simplices:
 - ★ ensures that orientation will be correct,
 - ★ allows for calculation of center of mass, measure, etc.

(Assumes that faces and cells are star-shaped w.r.t. average of their vertices).
- Entities (partially) created and added by increasing dimension:
 - ★ Vertices (no connectivity at this stage).
 - ★ Edges (connected to vertices and gives connexion between vertices).
 - ★ etc.



Conclusion and transition

- Building polytopal schemes requires:
 - ★ Selecting **degrees of freedom** (*polynomials on vertices, edges, faces, elements*).
 - ★ Implementing **reconstruction operators** as the solutions to **local problems** (*Riez representation problems*).

No need for explicit shape functions.

- Same approach can be applied to **(complex) finite elements**, without having to know their shape functions (*typically challenging in some FE for elasticity*).
- Coding polytopal methods is facilitated by a **rich mesh structure**, well-suited **polynomial bases** and efficient libraries for **polynomial integration**.





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Thank you for your attention!



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